

Selected references

- ▶ ESI Group
- ▶ University Hospital Pilsen (Czech Republic)
- ▶ Charles University (Czech Republic)
- ▶ OTH Regensburg (Germany)
- ▶ Institute for the Care of Mother and Child (Czech Republic)
- ▶ Aalborg University (Denmark)
- ▶ Criminalistic Institute in Prague (Czech Republic)
- ▶ Tianjin University of Science and Technology (China)
- ▶ Vision Consulting Technology (Czech Republic)
- ▶ Warsaw University of Technology (Poland)
- ▶ John H. & Amy Bowles Lawrence Foundation (USA)

- ▶ **APSN** Advanced Passive Safety Network (FP6)
- ▶ **APROSYS** Advanced Protective Systems (FP6)
- ▶ **MYMOSA** Motorcycle and Motorcyclist Safety (FP6)
- ▶ **SIM** Safety In Motion (FP6)
- ▶ **MOTORIST** Motorcycle Rider Integrated Safety (FP7)
- ▶ **COST TU1407** Scientific and technical innovations for safer Powered Two Wheelers (COST)
- ▶ **CZ-BY No. 38** Virtual human models for the prevention, therapy and rehabilitation of shoulder pathologies (ETC Goal 2014–2020)
- ▶ **CZ-BY No. 182** Obstetrics 2.0 – Virtual models for the prevention of injuries during childbirth (ETC Goal 2014-2020)
- ▶ **AMTMI** CZ.02.1.01/0.0/0.0/17_048/00072 80 Application of modern technologies in medicine and industry (ERDF)

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Customer focus

On-time delivery

Unmatched quality

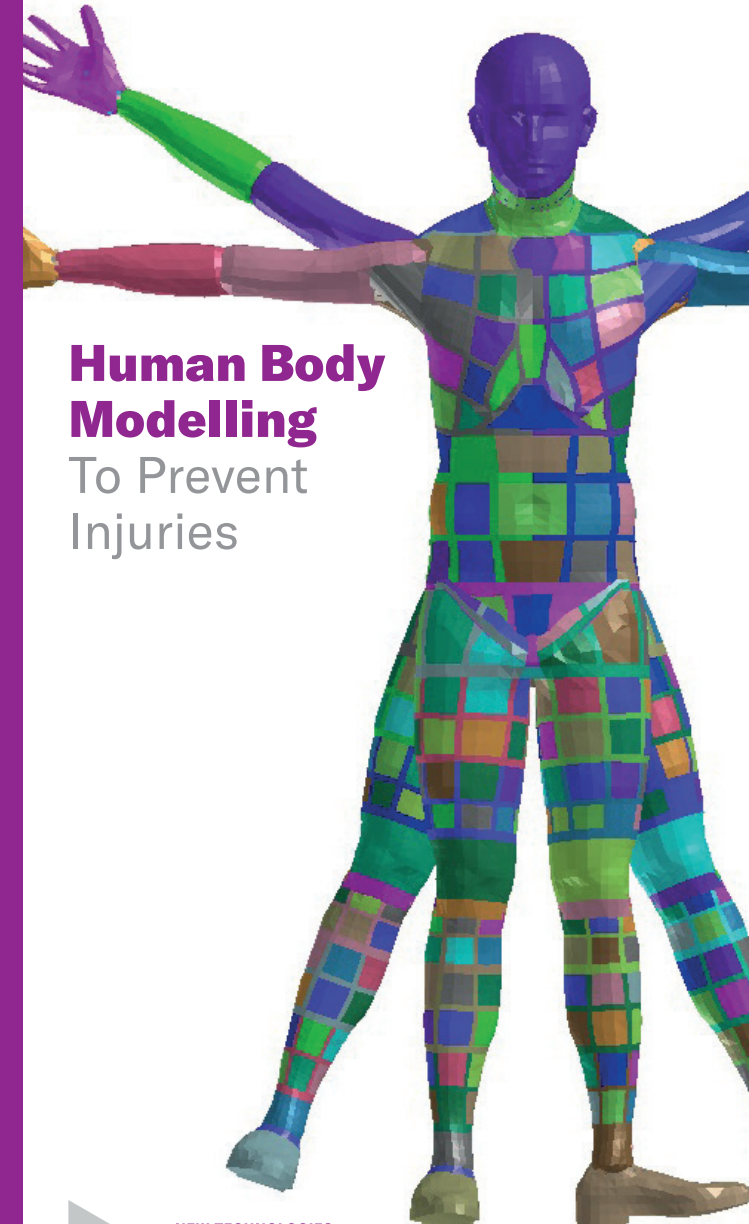
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Human Body Modelling
To Prevent Injuries



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Transport

- ▶ Models development
- ▶ Case and parametric studies
- ▶ Injury prediction
- ▶ Accident investigation
- ▶ Future mobility

Virthuman (VPS module)

- ▶ MBS model with compressible segments
- ▶ Anthropometric, age and gender scaling
- ▶ Simple positioning
- ▶ Fully validated
- ▶ Multi-purpose application
- ▶ Injury prediction based on EuroNCAP

Sport

- ▶ Musculoskeletal human body model
- ▶ Complex shoulder joint model
- ▶ Detailed hand model
- ▶ Force measurement using Kistler platform

Anybody modeling system

- ▶ Rigid bones, shapes based on MRI and CT
- ▶ Real joints anatomy and physiology
- ▶ Muscles attachments and trajectories, active model

Healthcare

- ▶ Human body – medical device interaction
- ▶ Prediction of injury during child delivery
- ▶ Influence of forceps, vacuum device
- ▶ Manual perineal protection
- ▶ Lower limb prosthesis optimization
- ▶ Deformable FEM models
- ▶ Implicit and explicit simulations
- ▶ Highly nonlinear models
- ▶ Characterization of soft tissue properties
- ▶ Corresponding measurements

